

The Coefficients of Dispersion and Dispersivity in Anisotropic Porous Media
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> We are considering the transport of a chemical species, at concentration c , in a phase occupying the void space (or part of it) in a porous medium (pm) domain.

> The total flux of that species (mass per unit area of porous Medium per unit time) is the sum of fluxes by advection, Dispersion and diffusion. Here we focus on **DISPERSION**.

> The dispersive flux, \mathbf{J} , is assumed to be expressed by a **Fickian-type law**:

$$J_i = -D_{ij} \frac{\partial c}{\partial x_j}, \quad i, j \equiv x, y, z, \quad \text{or} \quad i, j \equiv 1, 2, 3,$$

D_{ij} = dispersion coefficient, a 2nd rank tensor that relates the vector \mathbf{J} to the vector ∇c .

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❖ **BACKGROUND**

Since the early 60's, almost all research on (solute) dispersion has been limited to isotropic porous media. For such media, the components of the dispersivity tensor have been shown to depend only on two material moduli, referred to as **longitudinal and transversal dispersivities**. Based on the works of Robertson (1948) and Batchelor (1946), a study of the dispersivity for axially symmetric porous medium was conducted by Poreh (1965), leading to the conclusion that four material moduli are required to describe all components of the dispersivity coefficient, a_{ijkl} . In the last four decades, to our best knowledge, no theoretical work based on the inner symmetry of a_{ijkl} and external symmetry of porous media has been undertaken.

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> In thermodynamics, the rate of **entropy production** \dot{S} is related to the **thermodynamic driving force** \mathbf{X} and to the **thermodynamic flux**, \mathbf{Y} , called "conjugate Flux and Force", by

$$\dot{S} = \mathbf{X} \cdot \mathbf{Y}$$

> With $\mathbf{Y} = \chi \mathbf{J}$, and $\mathbf{X} = -\chi \nabla c$, we have:

$$\dot{S} = \chi \left[(-D_{ij} \frac{\partial c}{\partial x_j}) \right] \times \chi \left[(-\frac{\partial c}{\partial x_i}) \right] = \chi^2 D_{ij} \frac{\partial c}{\partial x_j} \frac{\partial c}{\partial x_i} > 0,$$

χ depends on the transported extensive property.

> Hence:

1. The matrix D_{ij} is positive definite.
2. The matrix D_{ij} is symmetric, i.e., $D_{ij} = D_{ji}$

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❖ **ISOTROPIC and ANISOTROPIC POROUS MEDIA**

ISOTROPIC $O(3)$ AXISYMMETRIC D_{oh}

ORTHO-RHOMBIC D_{2h} CUBIC O_h

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> The above conclusions are also valid for k_{ij} , \mathcal{D}_{ij}^* , λ_{ij}^*

However, D_{ij} depends also on the velocity, \mathbf{V} (and not only on the diffusive coefficient and the geometry of the phase in the void space).

> The coefficient of dispersion D_{ij} is related to the dispersivity, a_{ijkl} by:

$$D_{ij} = a_{ijkl} \frac{V_k V_l}{V}, \quad V = |\mathbf{V}|, \quad \mathbf{V} = (V_1, V_2, V_3)$$

> The coefficient a_{ijkl} is a 4th rank tensor, with the following properties:

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❖ **OBJECTIVE OF PRESENTATION**

To discuss the coefficients of **dispersion** and **dispersivity** in anisotropic porous media, focusing on axially symmetric porous media, e.g., a stratified porous medium. We show that in such a medium, the dispersivity is governed by **six independent moduli which have to satisfy certain constraints**. We also show that at least two independent experiments are required in order to obtain the values of these moduli for any 3D porous medium domain.

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1. From the requirement that the **rate of entropy production**, \dot{S} , expressed as

$$\dot{S} = Y_i X_i = \chi (-D_{ij} \frac{\partial c}{\partial x_j}) \times \chi (-\frac{\partial c}{\partial x_i}) = \chi^2 a_{ijkl} \frac{V_k V_l}{V} \frac{\partial c}{\partial x_j} \frac{\partial c}{\partial x_i} \geq 0,$$

be positive definite, it follows that a_{ijkl} is also **positive definite**.

2. Permutation in indices: $a_{ijkl} = a_{ijlk}$, $a_{ijkl} = a_{jkl i}$

> Hence, a_{ijkl} has 36 independent components and $2^6 - 1 = 63$ constraints should be satisfied.

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❖ ISOTROPIC porous media:

$$a_{ijkl} = a_T \delta_{ij} \delta_{kl} + \frac{a_L - a_T}{2} (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk})$$

$$D_{im} = a_T V \delta_{im} + (a_L - a_T) \frac{V V_m}{V}$$

a_L Longitudinal dispersivity
 a_T Transversal dispersivity

➤ Special case : Uniform horizontal flow:

$$V_1 = V, V_2 = V_3 = 0, \quad D_{ij} = \begin{pmatrix} a_L & 0 & 0 \\ 0 & a_T & 0 \\ 0 & 0 & a_T \end{pmatrix}$$

The matrix is positive if $a_L, a_T \geq 0$.

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❖ ANISOTROPIC POROUS MEDIUM, WITH UNIAXIAL SYMMETRY (Transverse isotropy)

➤ For this case, with \mathbf{e} (comp. \mathbf{e}_j), indicating the axis of symmetry, there exist six independent moduli, \mathbf{a}_i

The dispersivity & dispersion are expressed as:

$$a_{ijkl} = a_1 \delta_{ij} \delta_{kl} + \frac{a_2}{2} (\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}) + a_3 e_i e_j \delta_{kl} + a_4 e_k e_l \delta_{ij} + \frac{a_5}{2} (e_i e_k \delta_{jl} + e_j e_k \delta_{il} + e_i e_l \delta_{jk} + e_j e_l \delta_{ik}) + a_6 e_i e_j e_k e_l$$

$$VD_{ij} = a_1 V^2 \delta_{ij} + a_2 V_i V_j + a_3 \mathbf{V}^2 e_i e_j + a_4 (\mathbf{e} \cdot \mathbf{V})^2 \delta_{ij} + a_5 (\mathbf{e} \cdot \mathbf{V})(V_i e_j + e_i V_j) + a_6 (\mathbf{e} \cdot \mathbf{V})^2 e_i e_j,$$

where $(\mathbf{e} \cdot \mathbf{V})$ denotes a scalar product of the two vectors,

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➤ The \mathbf{a}_i 's, $1 \leq i \leq 6$, are the dispersivity moduli, which satisfy the six inequalities:

$$a_1 + a_2 + a_3 + a_4 + 2a_5 + a_6 > 0, \quad a_1 > 0,$$

$$a_1 + a_2 > 0, \quad a_1 + a_3 > 0, \quad a_1 + a_4 > 0,$$

$$a_1^2 + a_1(3a_2 + a_3 + a_4 + 2a_5 + a_6) + 2a_2(a_3 + a_4 + a_6) > 2a_5^2.$$

➤ Example 1: Axis of symmetry-- \mathbf{z}
 Uniform flow in the \mathbf{e}_3 ($\equiv \mathbf{z}$)-direction:

$$e_1 = e_2 = 0, e_3 = 1, \quad V_1 = V_2 = 0, V_3 = V.$$

Then:

$$D_{ij} = \begin{pmatrix} a_{TH}^v & 0 & 0 \\ 0 & a_{TH}^v & 0 \\ 0 & 0 & a_{LV}^v \end{pmatrix} V, \quad a_{TH}^v = a_1 + a_4$$

$$a_{LV}^v = a_1 + a_2 + a_3 + a_4 + 2a_5 + a_6$$

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a_{TH}^v = transverse dispersivity in the horizontal direction when flow is along vertical axis of symmetry

a_{LV}^v = longitudinal dispersivity in the vertical direction when flow is normal to vertical axis of symmetry

➤ Example 2: Axis of symmetry-- \mathbf{x}
 Uniform flow in the \mathbf{x} -direction

$$e_1 = e_2 = 0, e_3 = 1, \quad V_1 = V, V_2 = V_3 = 0$$

$$D_{ij} = \begin{pmatrix} a_{TH}^H & 0 & 0 \\ 0 & a_{TH}^H & 0 \\ 0 & 0 & a_{TV}^H \end{pmatrix} V, \quad a_{TH}^H = a_1 + a_2, a_{TV}^H = a_1 + a_3,$$

a_{TH}^H, a_{TV}^H = transverse dispersivities in the horizontal and in the vertical directions when flow is horizontal.

a_{LH}^H = longitudinal dispersivity in the horizontal direction when flow is horizontal.

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➤ Example 3: $V_1 = 0, V_2 = V_3 = V, e_1 = 1, e_2 = e_3 = 0$.

In this case:

$$D_{11} = 2(a_1 + a_3)V, \quad D_{22} = D_{33} = (2a_1 + a_2)V,$$

$$D_{23} = a_2V, \quad D_{12} = D_{31} = 0.$$

Here, we need three moduli: a_1, a_2, a_3 .

➤ Example 4: $V_1 = V_2 = V, V_3 = 0, e_1 = 1, e_2 = e_3 = 0$.

In this case:

$$D_{11} = (2a_1 + a_2 + 2a_3 + a_4 + 2a_5 + a_6)V, \quad D_{12} = (a_2 + a_5)V,$$

$$D_{22} = (2a_1 + a_2 + a_4)V, \quad D_{33} = (2a_1 + a_4)V, \quad D_{21} = D_{31} = 0.$$

Here, we have three additional moduli: a_4, a_5, a_6 .

➤ Thus, with two experiments, with different setups of \mathbf{V} and a known \mathbf{e} , we can find the six dispersivity moduli

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❖ EXPERIMENTAL DETERMINATION OF DISPERSIVITY MODULI

➤ We consider the two 6-dim vectors,

$$\mathbf{D}_6 = (D_{11}, D_{22}, D_{33}, D_{12}, D_{23}, D_{31}),$$

$$\mathbf{a}_6 = (a_1, a_2, a_3, a_4, a_5, a_6)$$

and their transposed counterparts, $\mathbf{D}_6^T, \mathbf{a}_6^T$

➤ We can then relate the two vectors by

$$\mathbf{V} \mathbf{D}_6^T = \mathbf{a}_6^T \Delta_1(\mathbf{V}, \mathbf{e}) = \begin{pmatrix} V^2 & V_1^2 & e_1^2 V^2 & (\mathbf{e} \cdot \mathbf{V})^2 & 2(\mathbf{e} \cdot \mathbf{V})e_1 V_1 & (\mathbf{e} \cdot \mathbf{V})^2 e_1^2 \\ V^2 & V_2^2 & e_2^2 V^2 & (\mathbf{e} \cdot \mathbf{V})^2 & 2(\mathbf{e} \cdot \mathbf{V})e_2 V_2 & (\mathbf{e} \cdot \mathbf{V})^2 e_2^2 \\ V^2 & V_3^2 & e_3^2 V^2 & (\mathbf{e} \cdot \mathbf{V})^2 & 2(\mathbf{e} \cdot \mathbf{V})e_3 V_3 & (\mathbf{e} \cdot \mathbf{V})^2 e_3^2 \\ 0 & V_1 V_2 & e_1 e_2 V^2 & 0 & (\mathbf{e} \cdot \mathbf{V})(e_2 V_1 + e_1 V_2) & (\mathbf{e} \cdot \mathbf{V})^2 e_1 e_2 \\ 0 & V_2 V_3 & e_2 e_3 V^2 & 0 & (\mathbf{e} \cdot \mathbf{V})(e_3 V_2 + e_2 V_3) & (\mathbf{e} \cdot \mathbf{V})^2 e_2 e_3 \\ 0 & V_3 V_1 & e_3 e_1 V^2 & 0 & (\mathbf{e} \cdot \mathbf{V})(e_1 V_3 + e_3 V_1) & (\mathbf{e} \cdot \mathbf{V})^2 e_3 e_1 \end{pmatrix}$$

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➤ Assume that the symmetry axis, \mathbf{e} is known and so is the velocity \mathbf{V} in a known frame of reference, $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3$

➤ By examining the matrix $\Delta_1(\mathbf{V}, \mathbf{e})$

$$\det \Delta_1(\mathbf{V}, \mathbf{e}) = 0, \quad \text{rank} \Delta_1(\mathbf{V}, \mathbf{e}) = 4.$$

➤ With the conclusion that

One cannot get all six dispersivity \mathbf{a}_i -moduli from a single experiment.

➤ Instead,

Two different experiments are required in order to determine all six \mathbf{a}_i -moduli

Example:

$$1^{\text{st}} \text{ exp.: } V_1 = 0, V_2 = V_3 = V \text{ and } e_1 = 1, e_2 = e_3 = 0.$$

$$\text{➤ Then } D_{11} = 2(a_1 + a_3)V, \quad D_{22} = D_{33} = (2a_1 + a_2)V,$$

$$D_{23} = a_2V, \quad D_{12} = D_{31} = 0.$$

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➤ 2nd exp.: $V_1 = V_2 = V, V_3 = 0$, and $e_1 = 1, e_2 = e_3 = 0$.

➤ Then

$$D_{11} = (2a_1 + a_2 + 2a_3 + a_4 + 2a_5 + a_6)V, \quad D_{12} = (a_2 + a_5)V,$$

$$D_{22} = (2a_1 + a_2 + a_4)V, \quad D_{33} = (2a_1 + a_4)V, \quad D_{23} = D_{31} = 0.$$

The above relationships, obtained from two independent experiments, with different setups of \mathbf{V} and a known \mathbf{e} , lead to the 6 \mathbf{a}_i -moduli in a 3D domain with uniaxial symmetry.

References

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